Tightly Coupled Accelerators Architecture

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What is “Tightly Coupled Accelerators (TCA)” ?

Concept:

- **Direct connection between accelerators (GPUs) over the nodes**
  - Eliminate extra memory copies to the host
  - Improve latency, improve strong scaling with small data size
- **Using PCIe as a communication device between accelerator**
  - Most accelerator devices and other I/O devices are connected by PCIe as end-point (slave device)
  - An intelligent PCIe device logically enables an end-point device to directly communicate with other end-point devices
- **PEACH2: PCI Express Adaptive Communication Hub ver. 2**
  - In order to configure TCA, each node is connected to other nodes through PEACH2 chip.

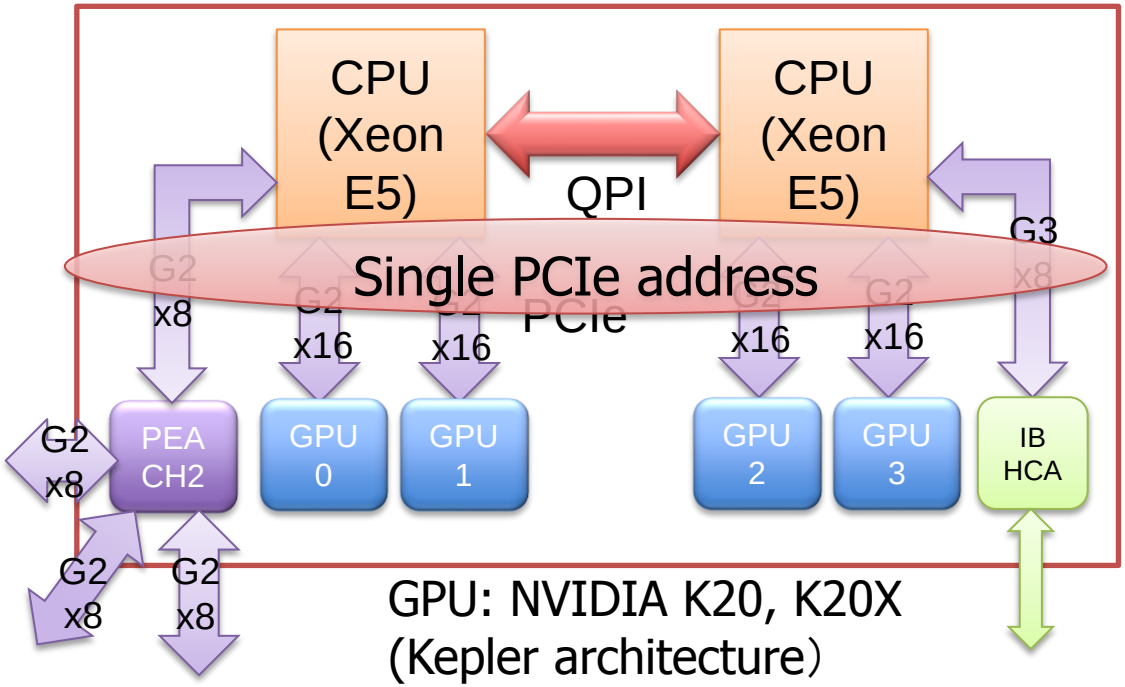
Design policy of PEACH2

- **Implement by FPGA with four PCIe Gen.2 IPs**
  - Altera Stratix IV GX
  - Prototyping, flexible enhancement
- **Sufficient communication bandwidth**
  - PCI Express Gen2 x8 for each port
  - Sophisticated DMA controller
    - Chaining DMA
- **Latency reduction**
  - Hardwired logic
  - Low-overhead routing mechanism
    - Efficient address mapping in PCIe address area using unused bits
    - Simple comparator for decision of output port

Not only is it proof-of-concept implementation, but it will also be available for product-run in GPU cluster.

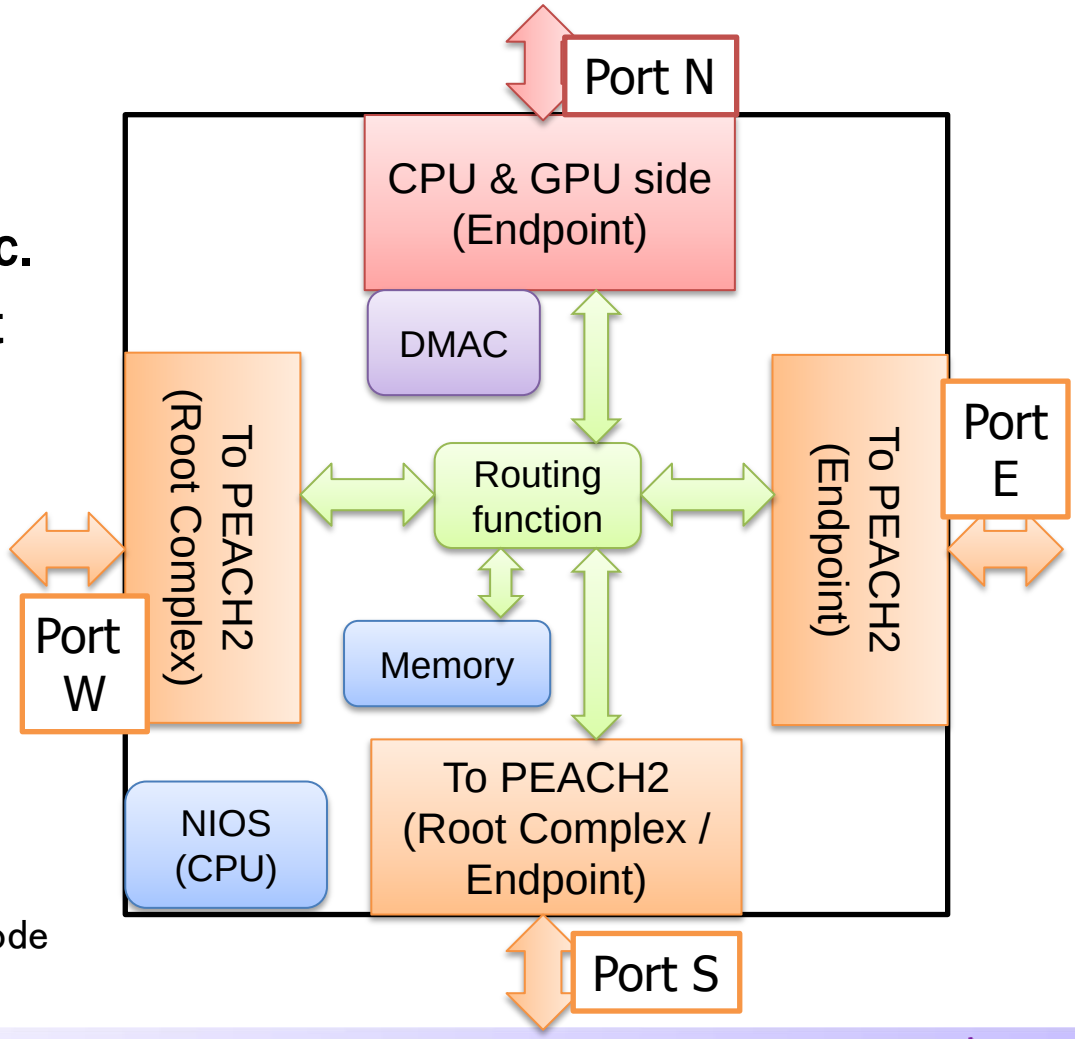
TCA node structure example

- **PEACH2 can access every GPUs**
  - NVIDIA Kepler architecture + CUDA 5.0 “GPUDirect Support for RDMA”
  - Performance over QPI is quite bad.
    => support only for GPU0, GPU1
- **Connect among 3 nodes using PEACH2**



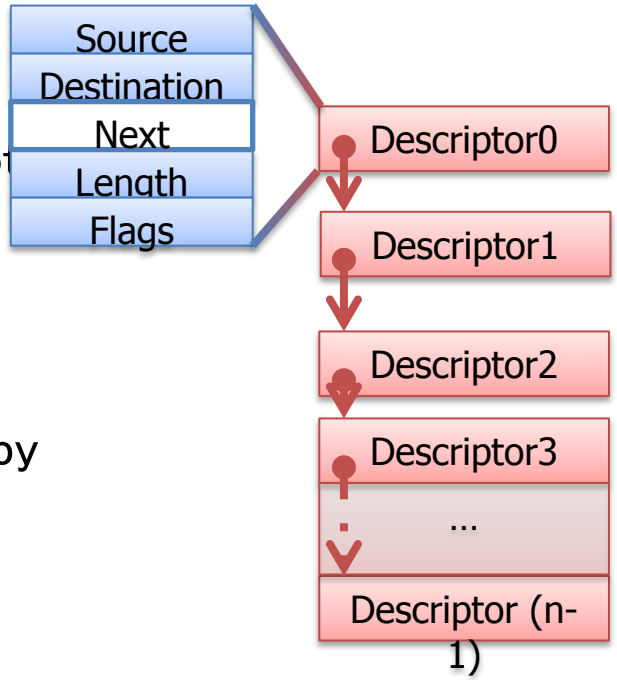
Overview of PEACH2 chip

- Fully compatible with PCIe Gen2 spec.
- Root and EndPoint must be paired according to PCIe spec.
- Port N: connected to the host and GPUs
- Port E and W: form the ring topology
- Port S: connected to the other ring
  - Selectable between Root and Endpoint
- Write only except Port N
  - Instead, "Proxy write" on remote node realizes pseudo-read.



Communication by PEACH2

- **PIO**
  - CPU can store the data to remote node directly using mmap.
- **DMA**
  - Chaining mode
    - DMA requests are prepared as the DMA descript chained in the host memory.
    - DMA transactions are operated automatically according to the DMA descriptors by hardware.
  - Register mode
    - DMA requests are registered into the PEACH2 by up to 16.
    - Lower overhead than chaining mode by omitting transfer for descriptors from host
  - Block stride transfer function



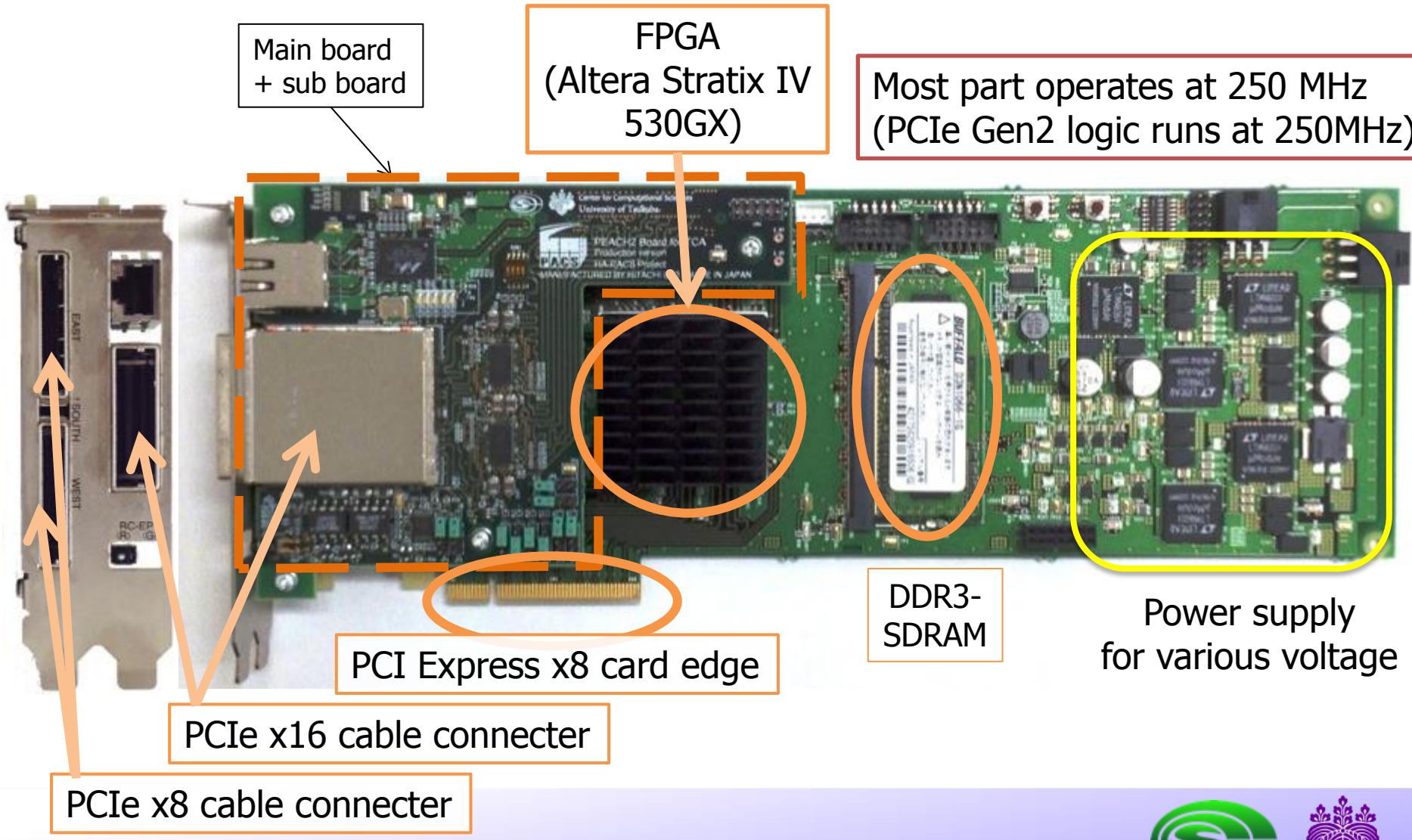
PEACH2 board (Production version for HA-PACS/TCA)

- **PCI Express Gen2 x8 peripheral board**
  - Compatible with PCIe Spec.

Side View

Top View

PEACH2 board (Production version for HA-PACS/TCA)



HA-PACS System

TCA: 5Rack x 2Line

LINPACK: 277TFlops (Efficiency 76%)

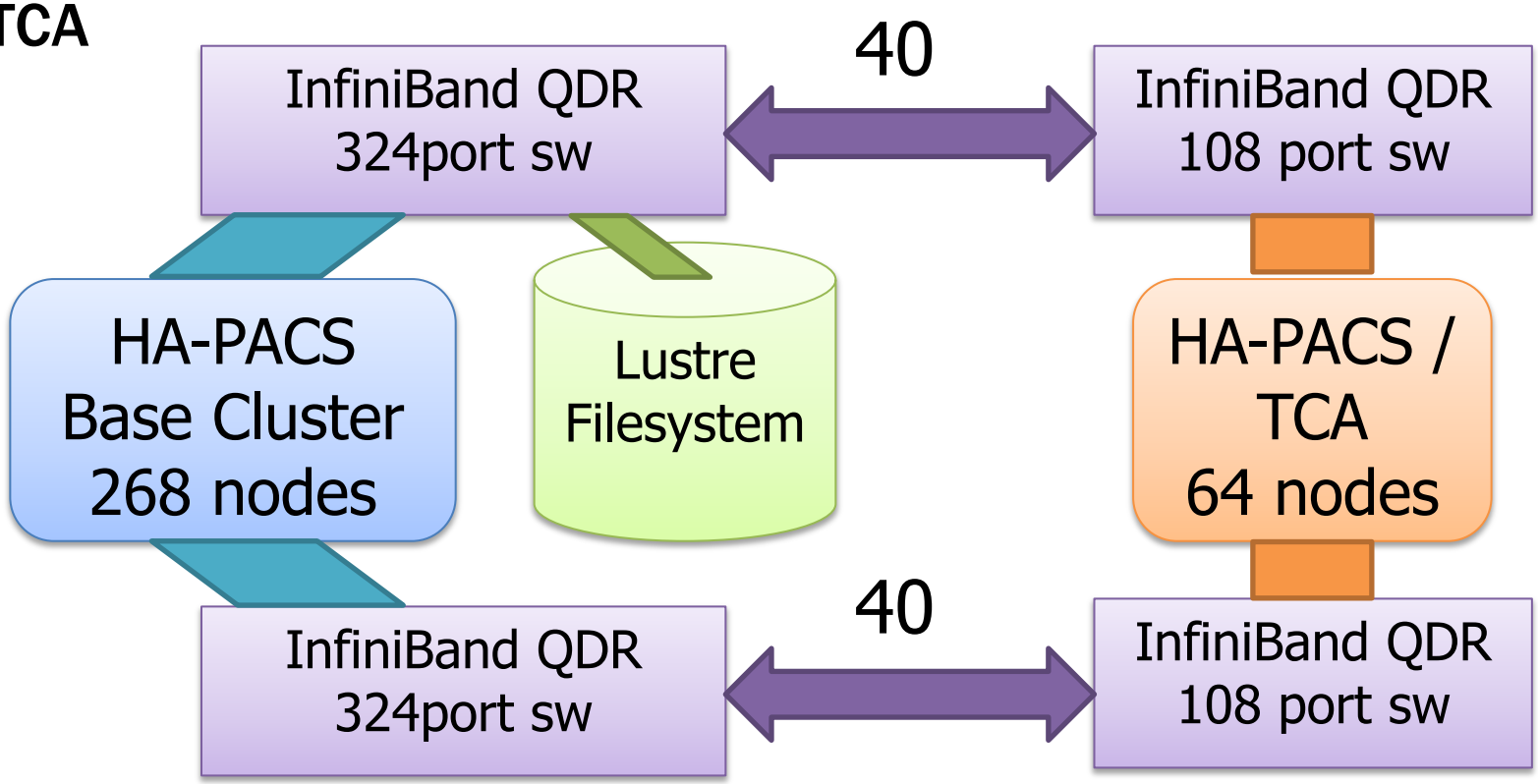
3.52GFLOPS/W #3 Green500 2013/11

TCA
since Nov. 2013

Base Cluster
since Feb. 2012

HA-PACS Total System

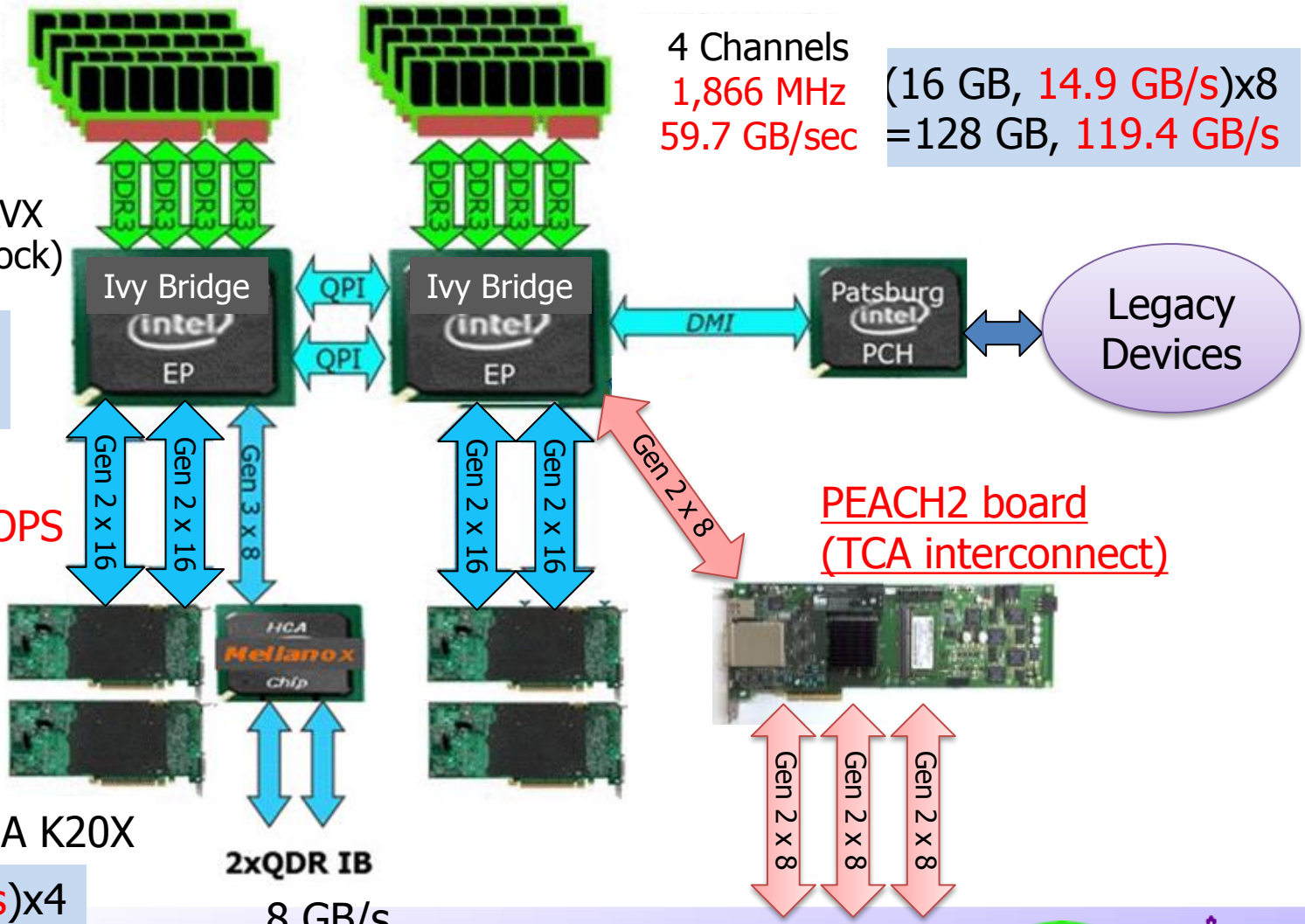
- **InfiniBand QDR 40port x 2ch between base cluster and TCA**



421 TFLOPS, Efficiency 54%,
41st 2012.6 Top500
1.15 GFLOPS/W

277 TFLOPS, Efficiency 76%,
134th 2013.11 Top500
3.52 GFLOPS/W 3rd 2013.11 Green500

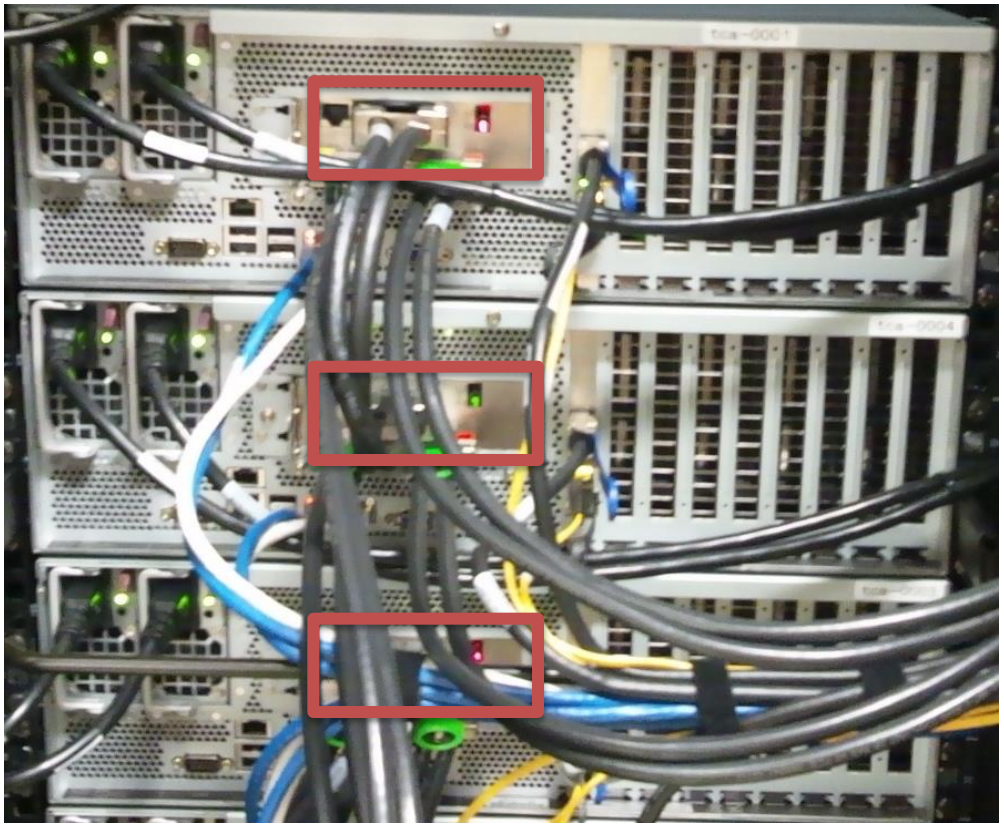
HA-PACS/TCA (Computation node)



HA-PACS/TCA

front view
(8 node/rack)
3U height

PEACH2 boards are installed and connected cables

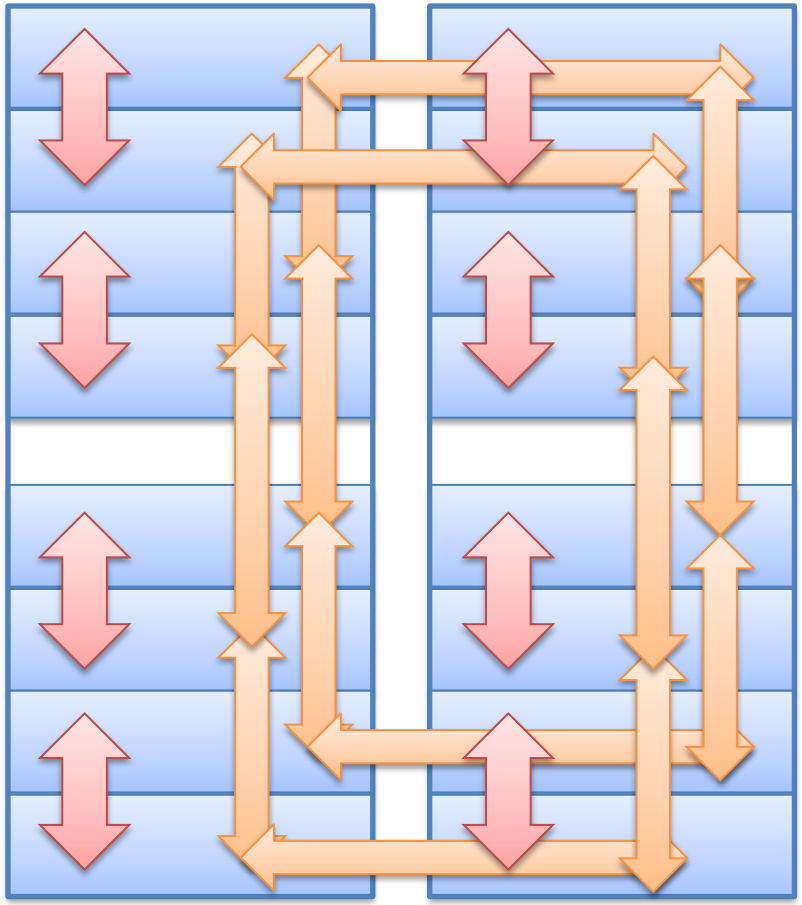


rear view

HA-PACS/TCA

TCA sub-cluster (16 nodes)

- **TCA has four sub-clusters, and TCA sub cluster consists of two racks.**
  - 2x8 torus (one example)
  - A ring consists of 8 nodes (between East port and West port, Orange links)
  - Two rings are connected at each node (between both South port, Red links)
- **We can use 32 GPUs in a sub-cluster seamlessly as same as multi-GPUs in a node.**
  - only use 2GPU in a node because of bottleneck of QPI
- **Sub-clusters are connected by IB(QDR 2port)**



Evaluation items

- **Ping-pong performance between nodes**
  - Latency and bandwidth
  - Written as application
  - Comparison with MVAPICH2 1.9 (with CUDA support) for GPU-GPU communication and MVAPICH2-GDR (with support GPU Direct support for RDMA) using IB (dual QDRx4 that bandwidth is twice of TCA)

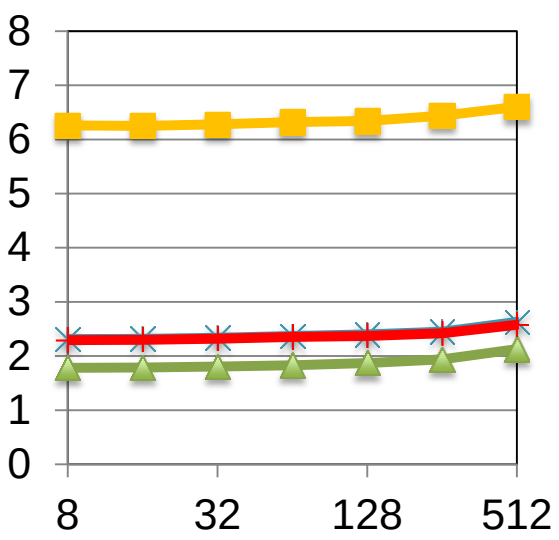
- In order to access GPU memory by the other device, "GPU Direct support for RDMA" in CUDA5 API is used.
  - Special driver named "TCA p2p driver" to enable memory mapping is developed.
- "PEACH2 driver" to control the board is also developed.

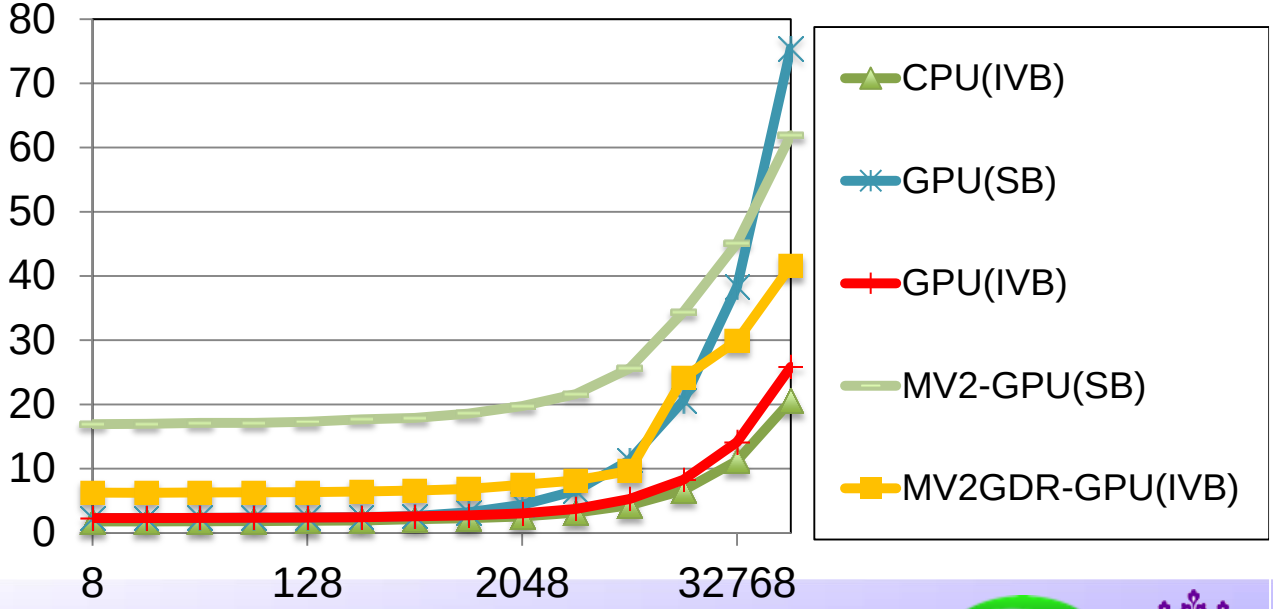
Ping-pong Latency

Minimum Latency

- PIO (CPU to CPU): 0.9us
- DMA:CPU to CPU: 1.9us
  GPU to GPU: 2.3us

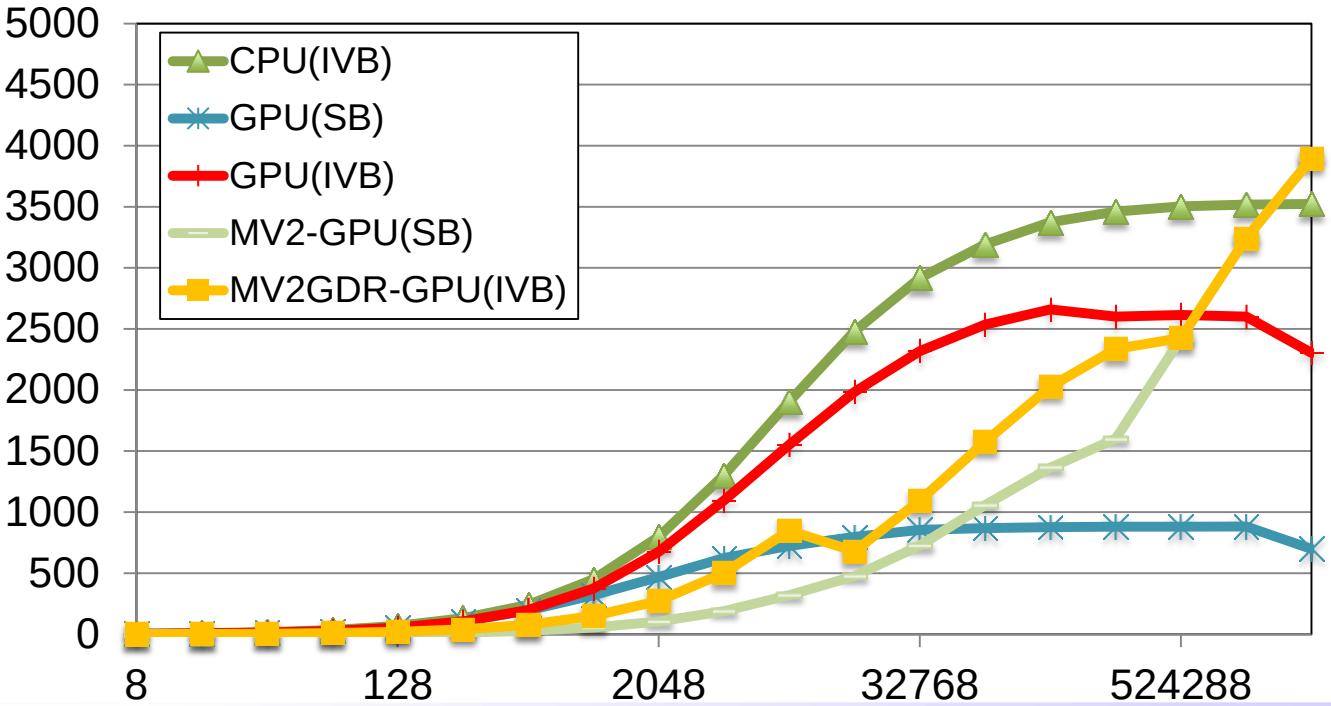
(cf. MVAPICH2 1.9:19 us
MVAPICH2-GDR: 6us)





Ping-pong Bandwidth

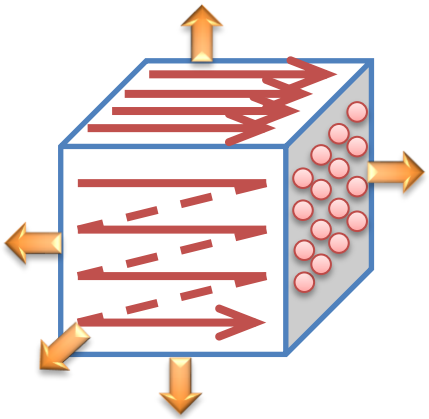
- **CPU-CPU DMA Max. 3.5GByte/sec（95% of theoretical peak）**
- **GPU-GPU DMA Max. 2.6GByte/sec**
  - GPU(SB) was saturated at 880MByte/sec because of poor performance of PCIe switch in CPU
  - GPU(IVB) is faster than MV2GDR less than 512KB message size



Programming for TCA cluster

- **Data transfer to remote GPU within TCA can be treated like multi-GPU in a node.**
- **In particular, suitable for stencil computation**
  - Good performance at nearest neighbor communication due to direct network
  - Chaining DMA can bundle data transfers for every "Halo" planes
    - XY-plane: contiguous array
    - XZ-plane: block stride
    - YZ-plane: stride
  - In each iteration, DMA descriptors can be reused and only a DMA kick operation is needed

=> <u>Improve strong scaling with small data size</u>



Bundle to 1 DMA

Current activities

- **Develop API for user programming**
  - similar to CudaMemcpy API. It enables use GPUs in a sub cluster seamlessly as same as Multi-GPUs in a node using CudaMemcpy API.
- **XMP for TCA**
  - cooperating with RIKEN AICS, we develop XMP for TCA.
- **Function offloading on TCA**
  - a reduction mechanism between GPUs in a sub cluster will be offloaded on TCA cooperating with Keio-Univ. Amano lab. and astrophysics group in CCS
- **QUDA (QCD libraries for CUDA)**
  - TCA feature will be added to QUDA cooperating with NVIDIA.

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Summary

- **TCA: Tightly Coupled Accelerators**
  - TCA enables direct communication among accelerators as an element technology becomes a basic technology for next gen's accelerated computing in exa-scale era.
- **PEACH2 board: Implementation for realizing TCA using PCIe technology**
  - Bandwidth: max. 3.5 Gbyte/sec between CPUs (over 95% of theoretical peak)
    Min. Latency: 0.9 us (PIO), 1.9 us (DMA between CPUs), 2.3 us (DMA between GPUs)
  - GPU-GPU communication over the nodes can be demonstrated with 16 node cluster.
  - By the ping-pong program, PEACH2 can achieve lower latency than existing technology, such as MVAPICH2 in small data size.
- **HA-PACS/TCA with 64 nodes was installed on the end of Oct. 2013.**
  - Actual proof system of TCA architecture with 4 GPUs per each node
  - Development of the HPC application using TCA, and production-run

Related Work

- **Non Transparent Bridge (NTB)**
  - NTB appends the bridge function to a downstream port of the PCI-E switch.
  - Inflexible, the host must recognize during the BIOS scan
  - It is not defined in the standard of PCI-E and is incompatible with the vendors.
- **APEnet+ (Italy)**
  - GPU direct copy using Fermi GPU, different protocol from TCA is used.
  - Latency between GPUs is around 5us?
  - Original 3-D Torus network, QSFP+ cable
- **MVAPICH2 + GPUDirect**
  - CUDA5 + Kepler
  - Latency between GPUs is reported as 6us.